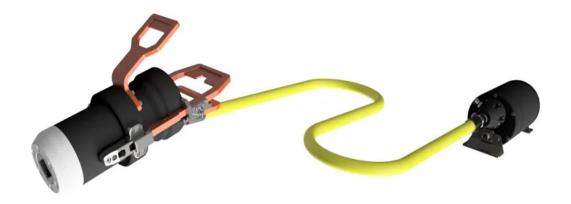
ELECTRICAL TORQUE TOOL

ROV INTERVENTION CLASS 1-4 (API 17D) HIGH PRECISION



Description

The Electrical Torque Tool is a module based, compact, flexible and robust precision tool for operation and use in all subsea and ROV applications.

The system combines all known advantages from a hydraulic torque tool system with the technology and advantages available from a modern based electrical controlled drive system.

Interface sockets are replaced on both deck and subsea (optional) to interface ISO class 1-4 interfaces. The different sockets will automatically interface the gear system to utilize the optimal gear ratio and power/speed capacity. The control system automatically switches between low torque and high torque mode.

Features Torque Tool

- Compact and low weight tool
- Min torque output 20 Nm
- Max torque output 2711 Nm
- Subsea socket changeout jig (optional)
- Low voltage 5A 110 VAC circuit
- Ixys Suite Control System
- Low torque at 350 Nm and 30 RPM
- □ High torque at 2711 Nm and 6 RPM
- Mechanical latching wings
- Mechanical turn indicator (backup)

Features Control System

- □ Ixys Suite modular Control System ™
- Automatically as found / as left still pictures
- Supports IP camera connection
- Torque and turns recording chart
- Gearbox Class 5/6/7
- Cloud based Valve Management System ™ *in development





SPECIFICATIONS

ELECTRICAL TORQUE TOOL

General Technical Specifications

Type Part Number Dimensions Pod Canister Dimensions ETT Tool ETT Pod Canister ETT Tool Weight in air / submerged

Specifications

Max Output Torque Max Speed

Electrical Interface

Power

Input

Communication

Interface Description

General Features Depht Rating Electrical Torque Tool ETT Ø185 mm L= 325 mm Ø190 mm L= 367 mm ~13 kg / ~5 kg ~34 kg / ~26 kg

2711 Nm 30 RPM

2 kW (to achieve 2700 Nm @ 6 RPM 2 kW is required) 110-230 VAC 50/60 Hz or 160-320 VDC +10/-15%

RS 232 Standard (RS485 and Ethernet upon request)

Burton Connector 5507 2008 8-pin connector

- 1 110/230VAC / 160/320 VDC
- 2 110-230VAC / 0 VDC
- 3 Chassis
- 4 N.C
- 5 RX RS 232
- 6 TX RS 232
- 7 N.C
- 8 Com./GND

MSW 3000

The specification details are illustrative for marketing purpose only. Actual equipment may be different as a result of product improvement or other reasons. Specific interface and performance information should be reconfirmed at time of order placement. Envirent AS, Robotvegen 16, 4340 Bryne, +47 477 77 500, post@envirent.no

